

FIG. 2

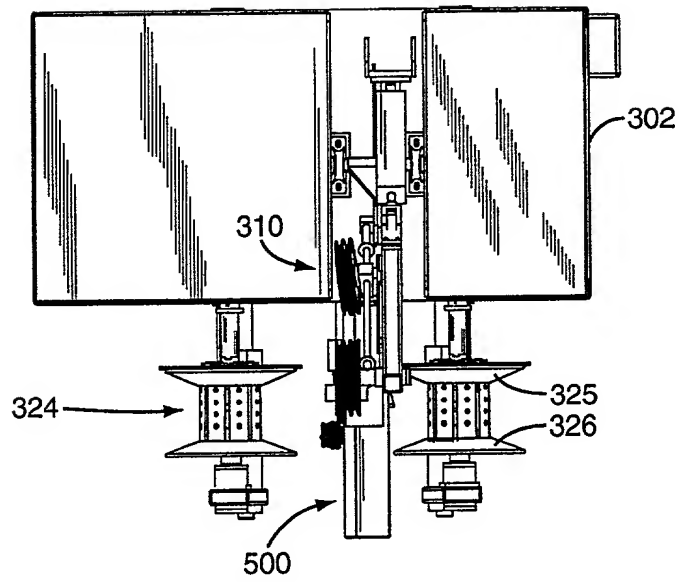


FIG. 3A

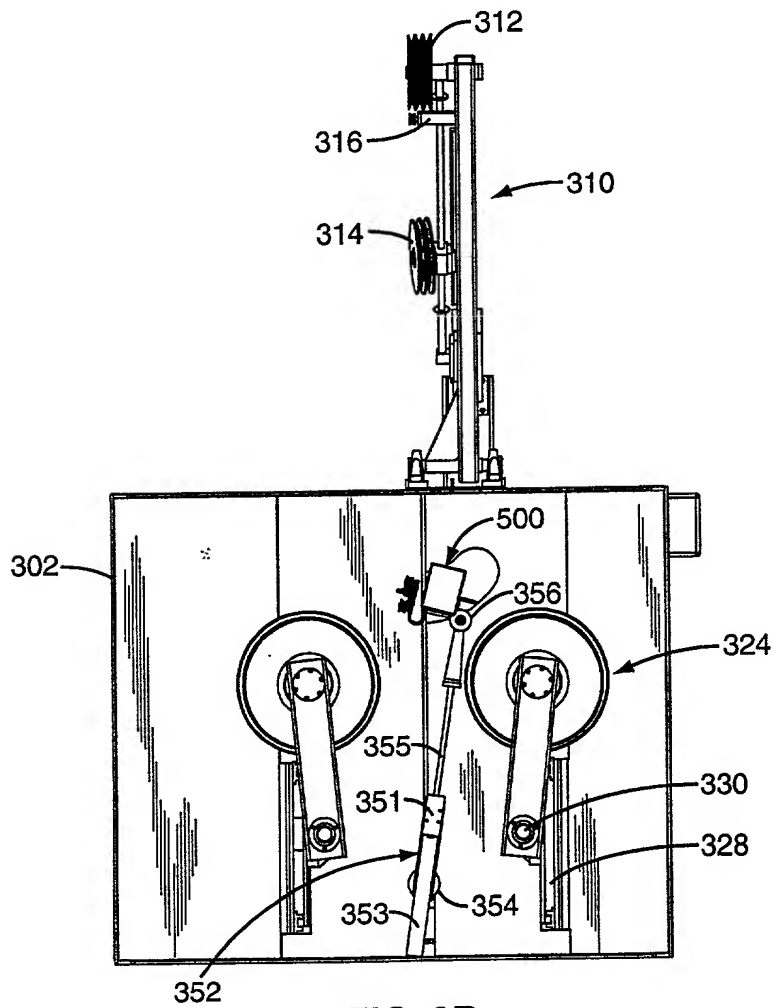


FIG. 3B

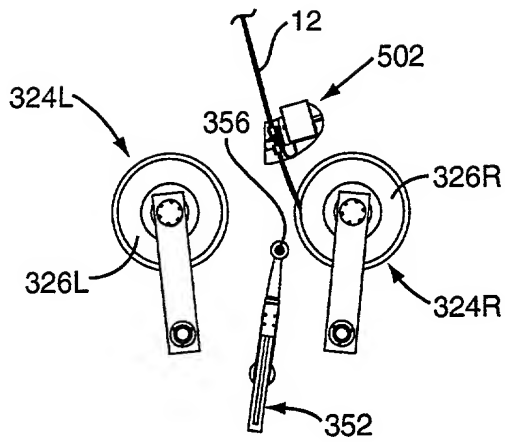


FIG. 4A

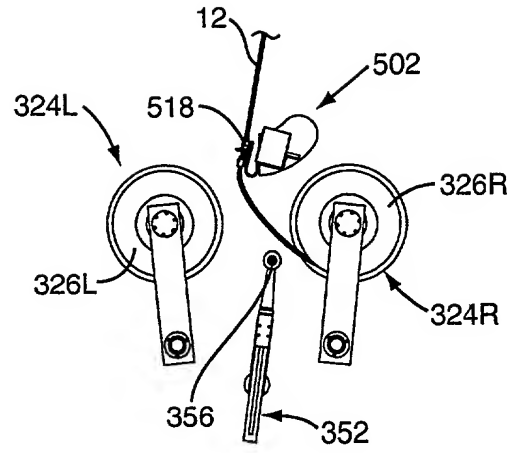


FIG. 4B

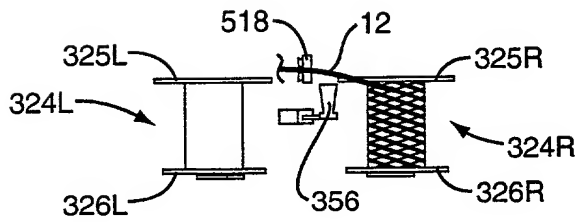


FIG. 4C

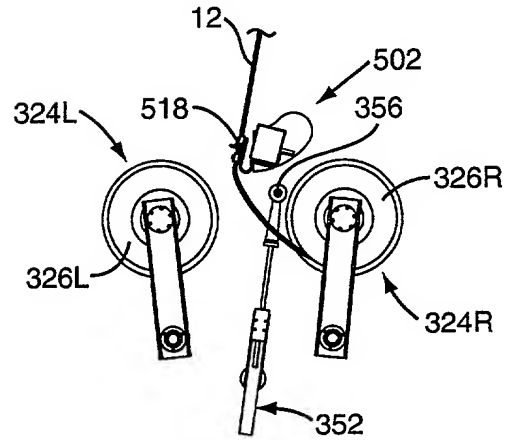


FIG. 4D

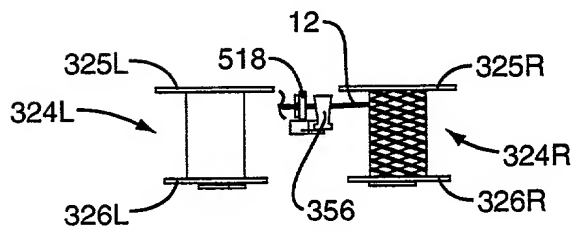


FIG. 4E

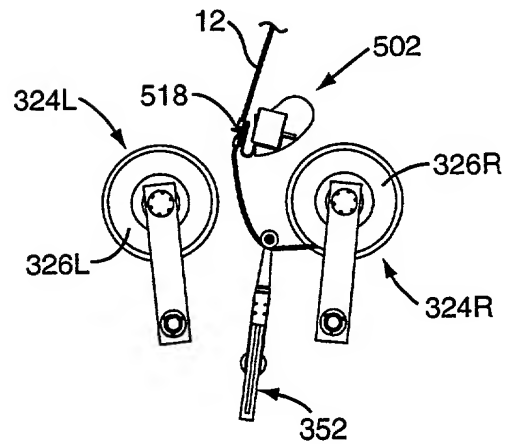


FIG. 4F

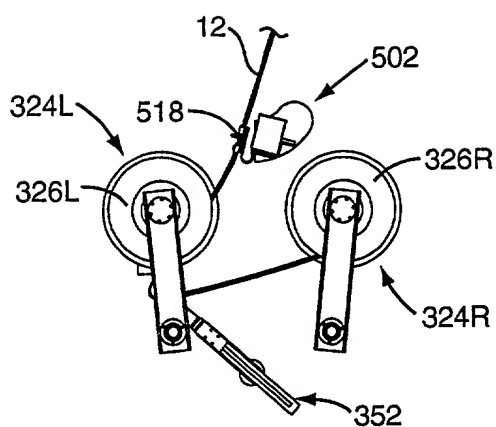


FIG. 4G

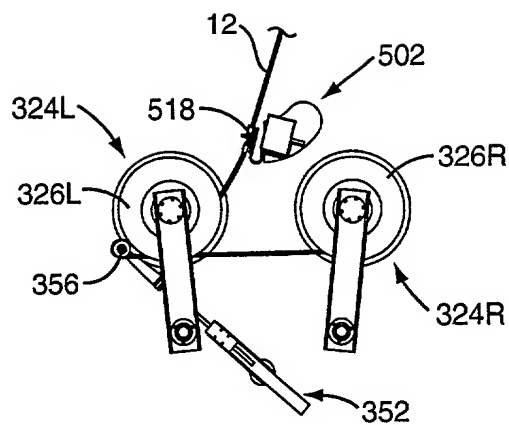


FIG. 4H

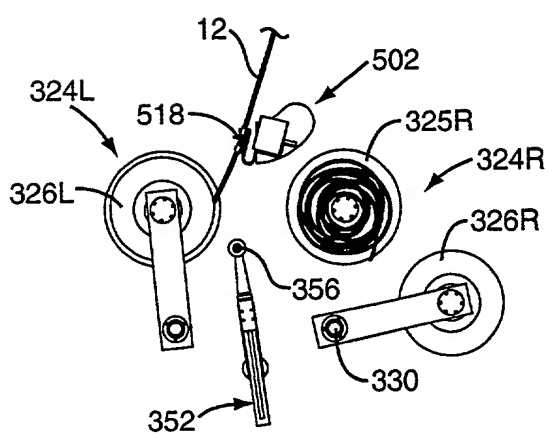


FIG. 4I

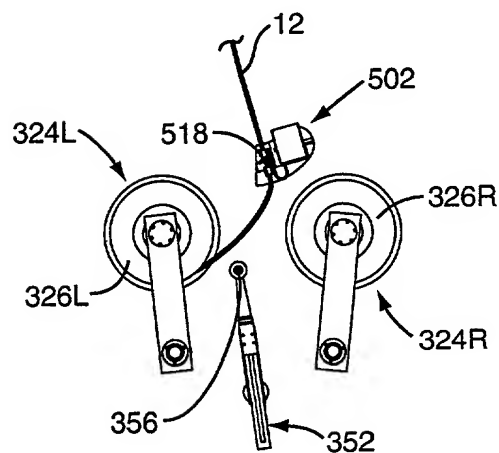


FIG. 4J

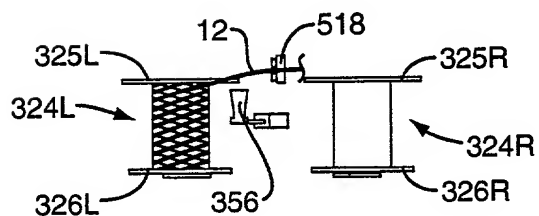


FIG. 4K

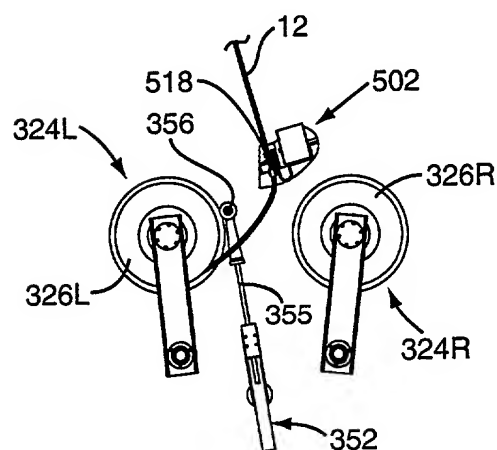


FIG. 4L

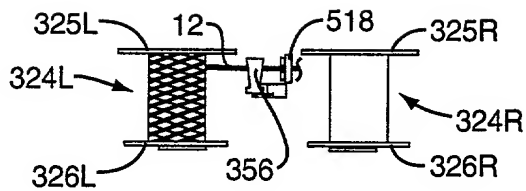


FIG. 4M

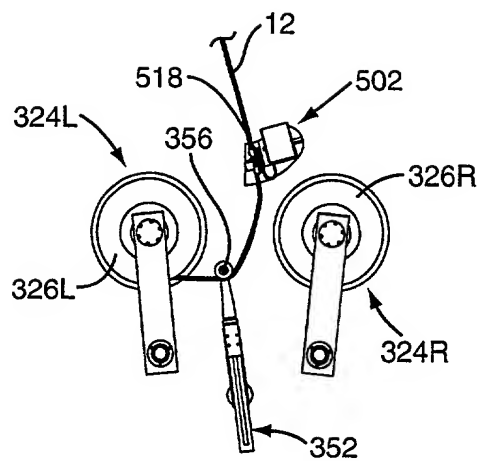


FIG. 4N

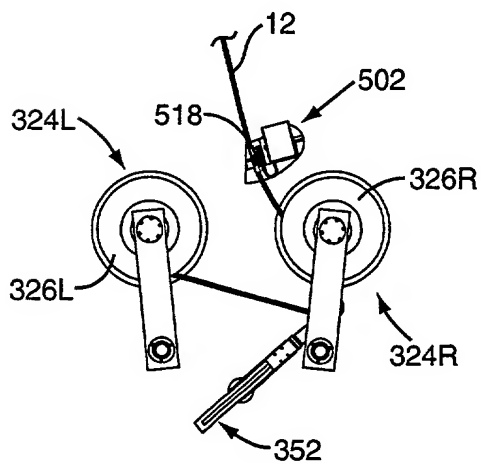


FIG. 4O

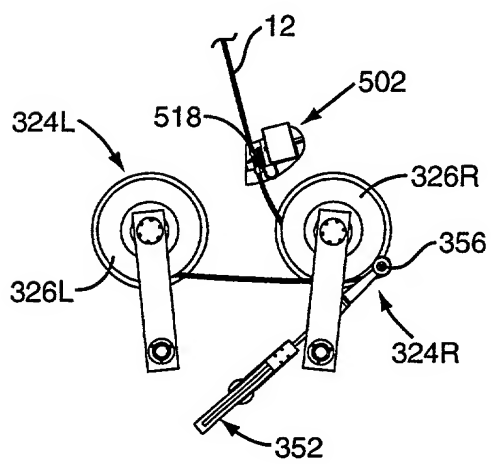


FIG. 4P

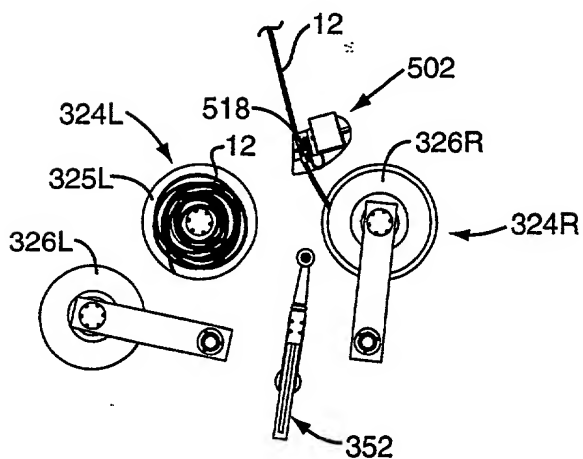


FIG. 4Q

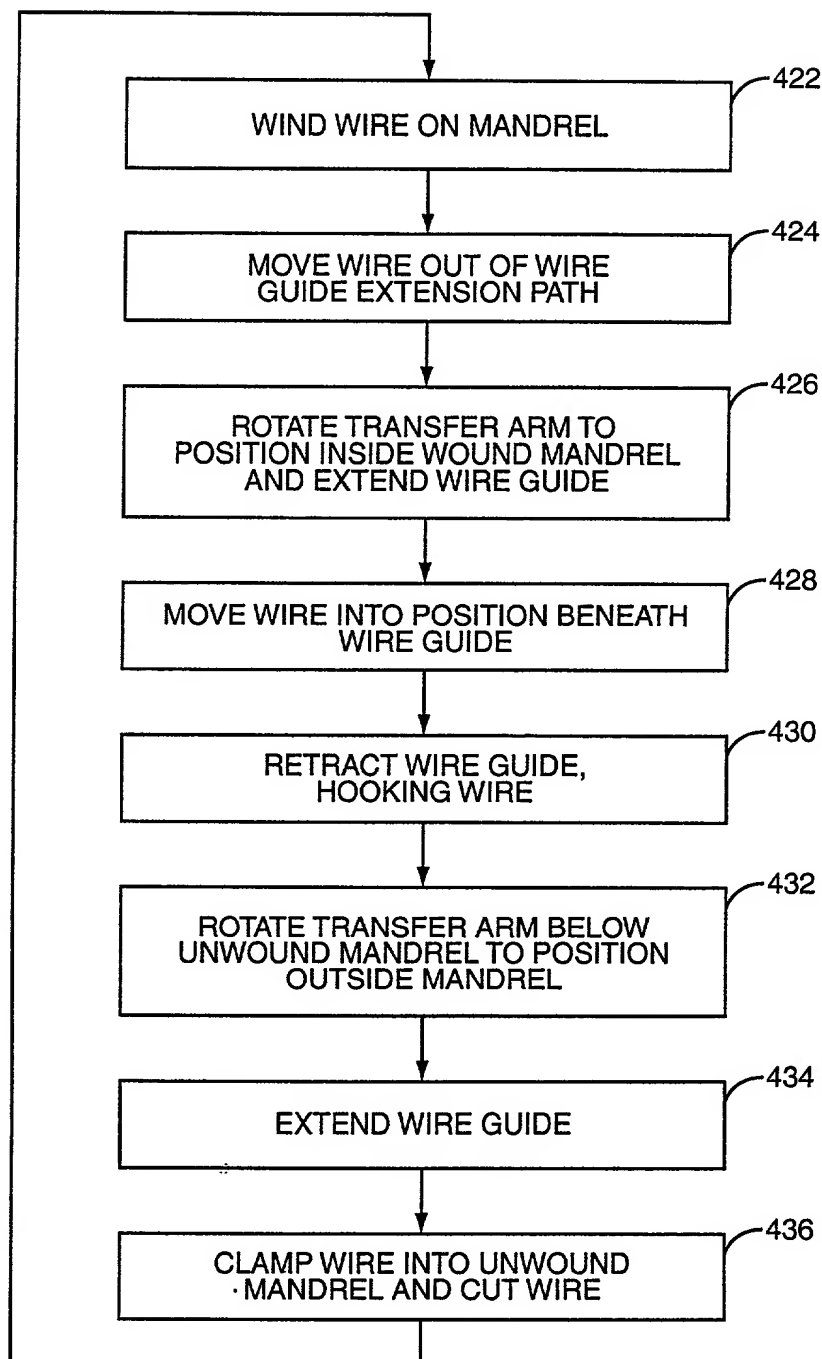


FIG. 5

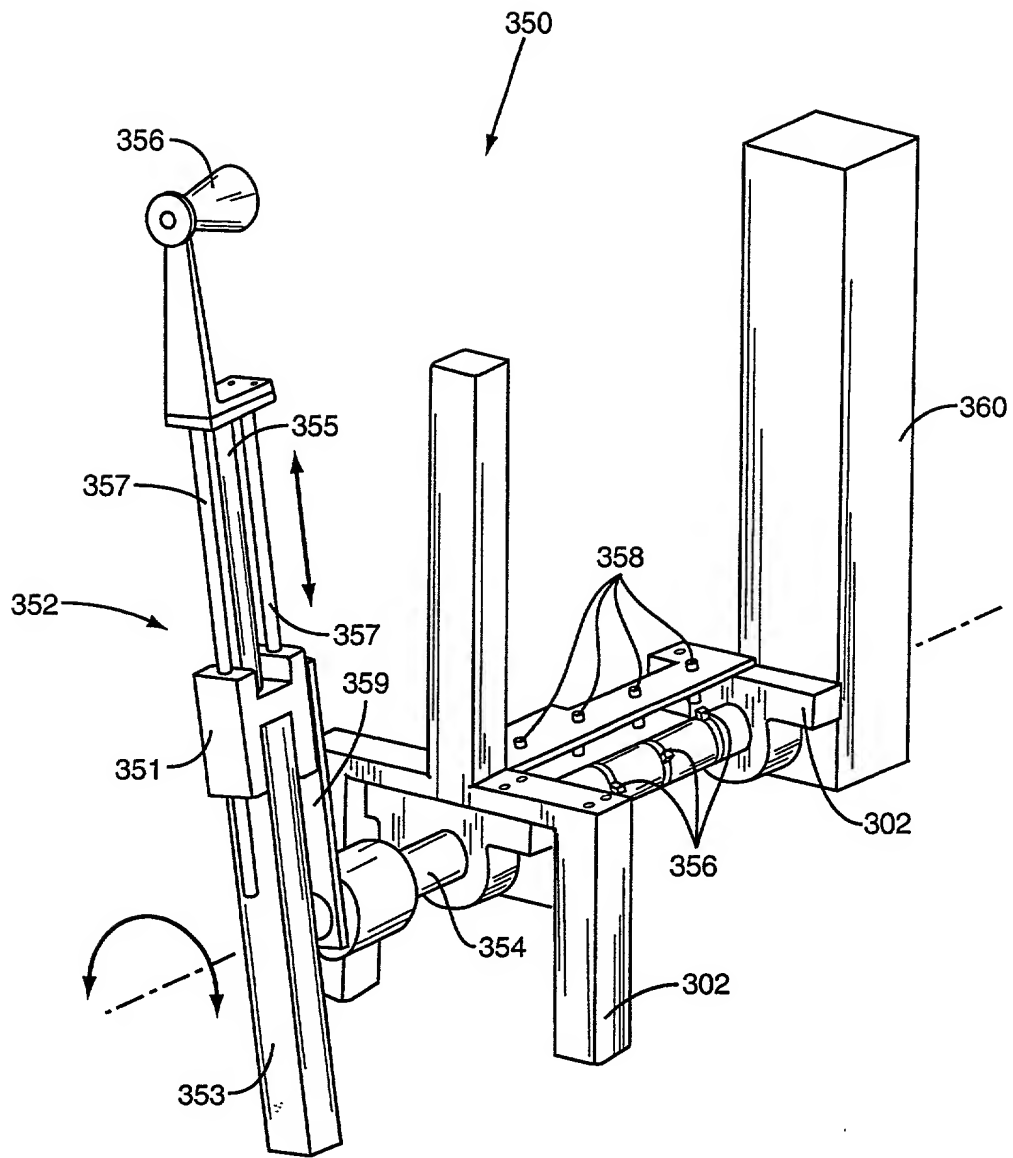


FIG. 6

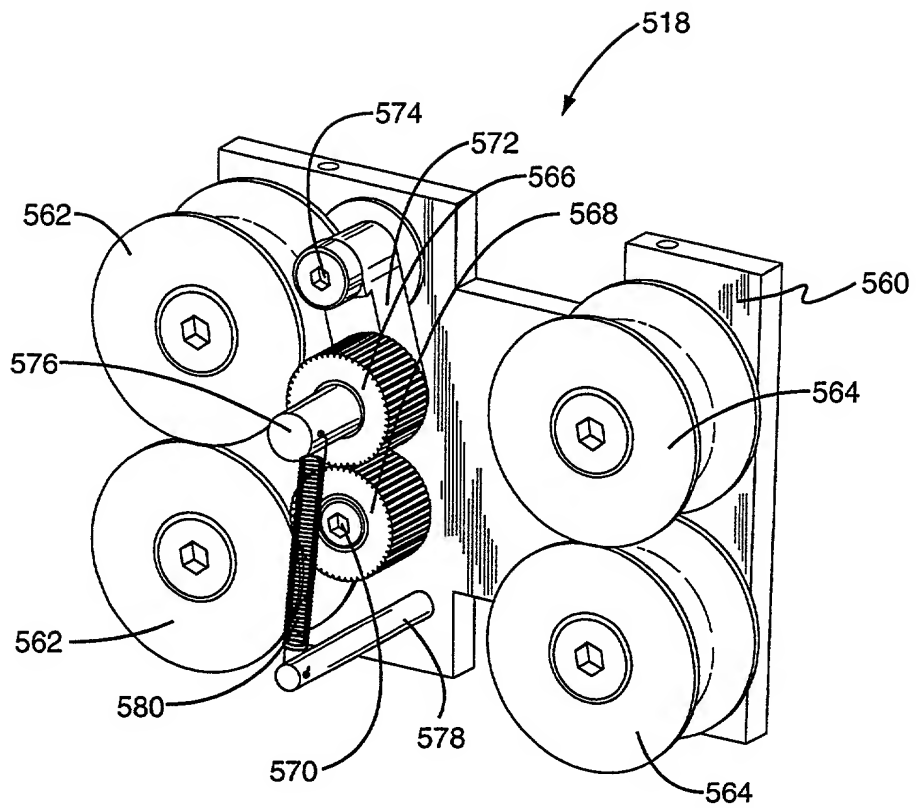


FIG. 8A

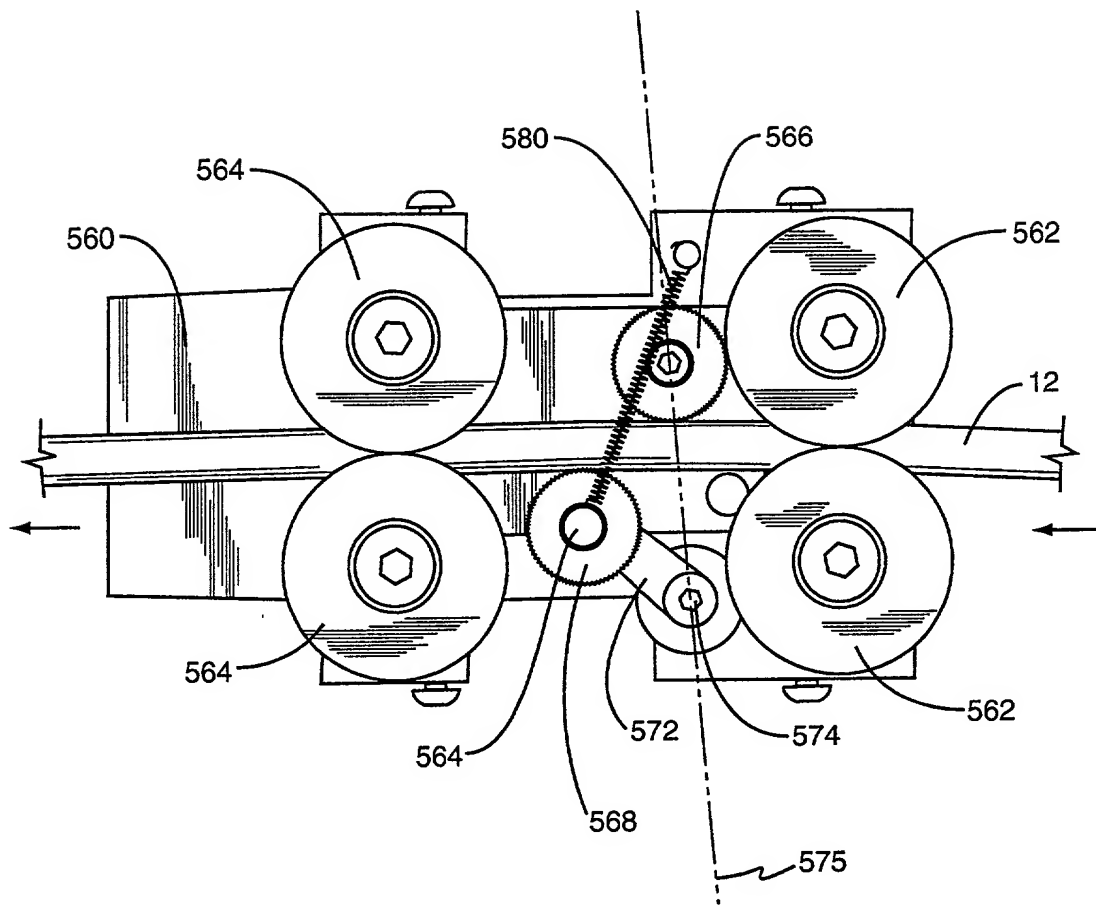


FIG. 8B

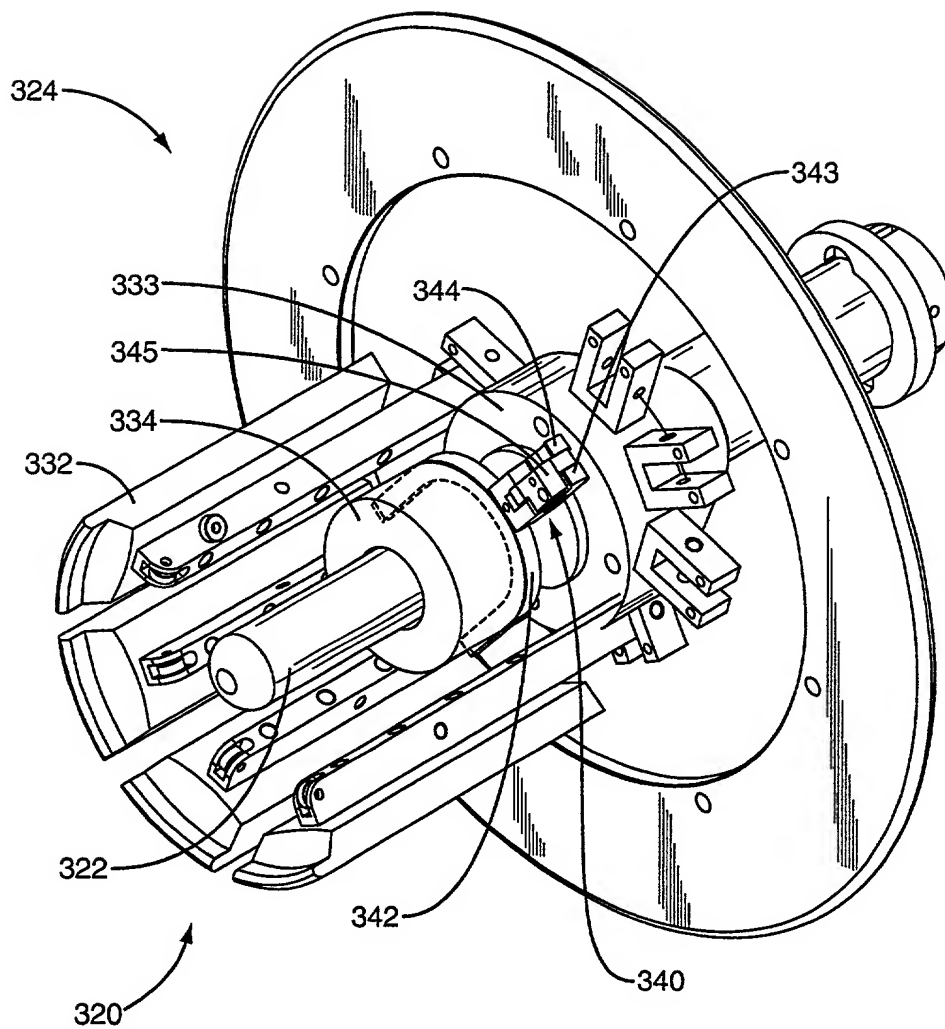


FIG. 9

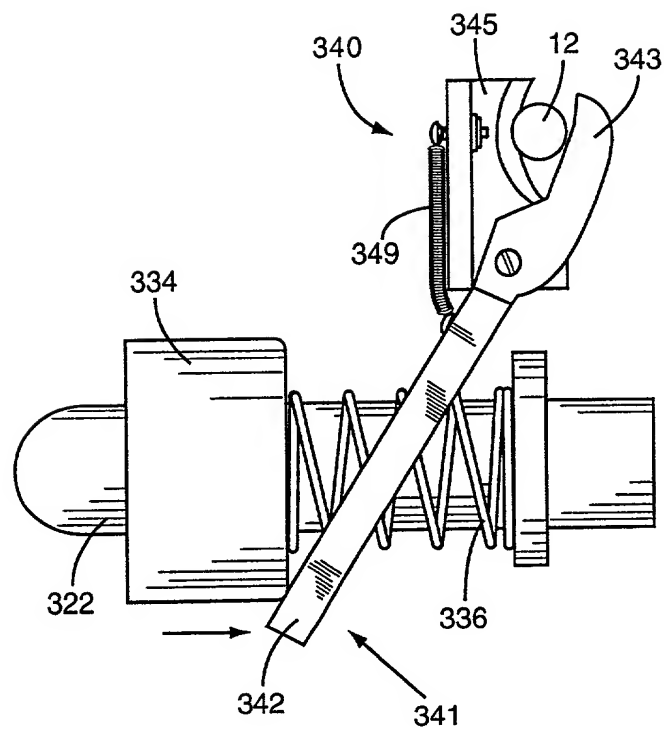


FIG. 10A

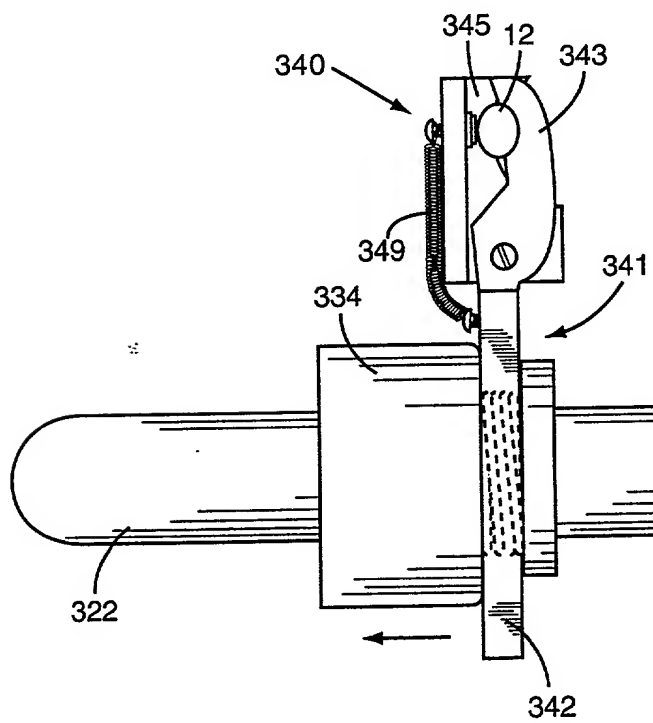


FIG. 10B

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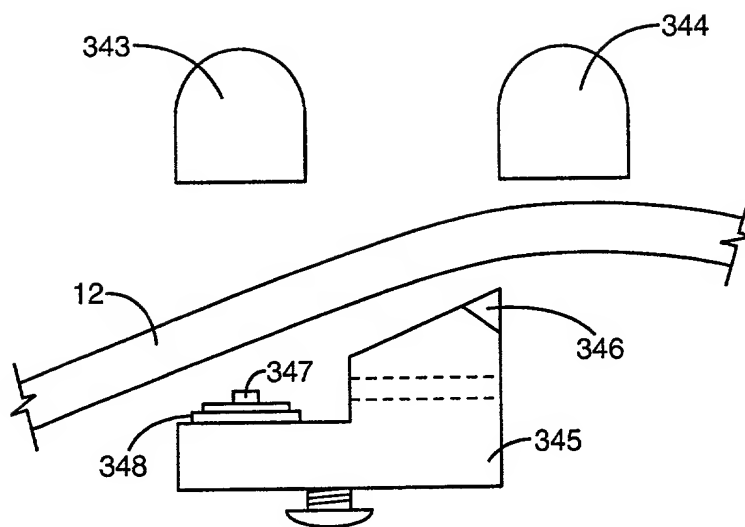


FIG. 11A

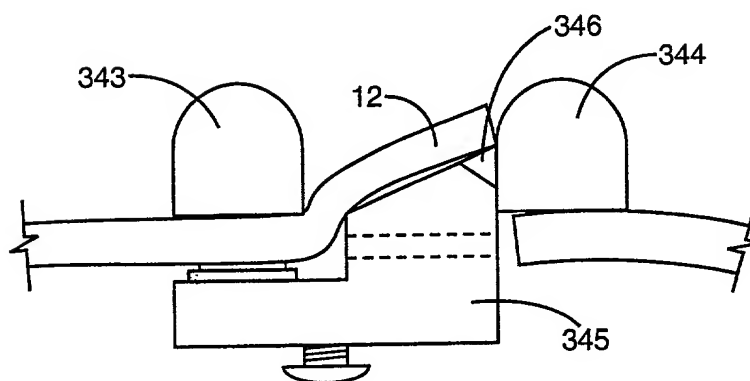


FIG. 11B

FIG. 1 is a perspective view of a cable-driven system 200. The system includes a vertical frame 218 with a top plate 222 and a bottom plate 214. A cable 12 is guided by a pulley 210 on the right, a pulley 212 on the left, and a pulley 216 in the center. A cable 224 is also shown. A cable 223 is connected to the top plate 222. A cable 220 is also shown.

* 200000 400000 600000 800000 1000000 1200000 1400000 1600000 1800000 2000000

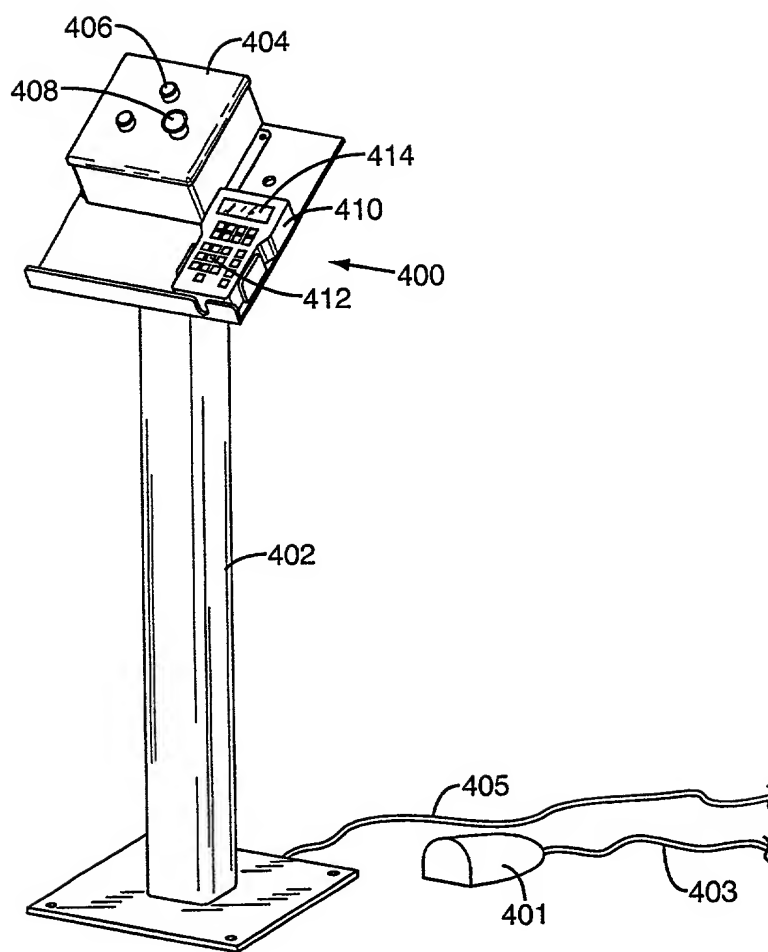


FIG. 13

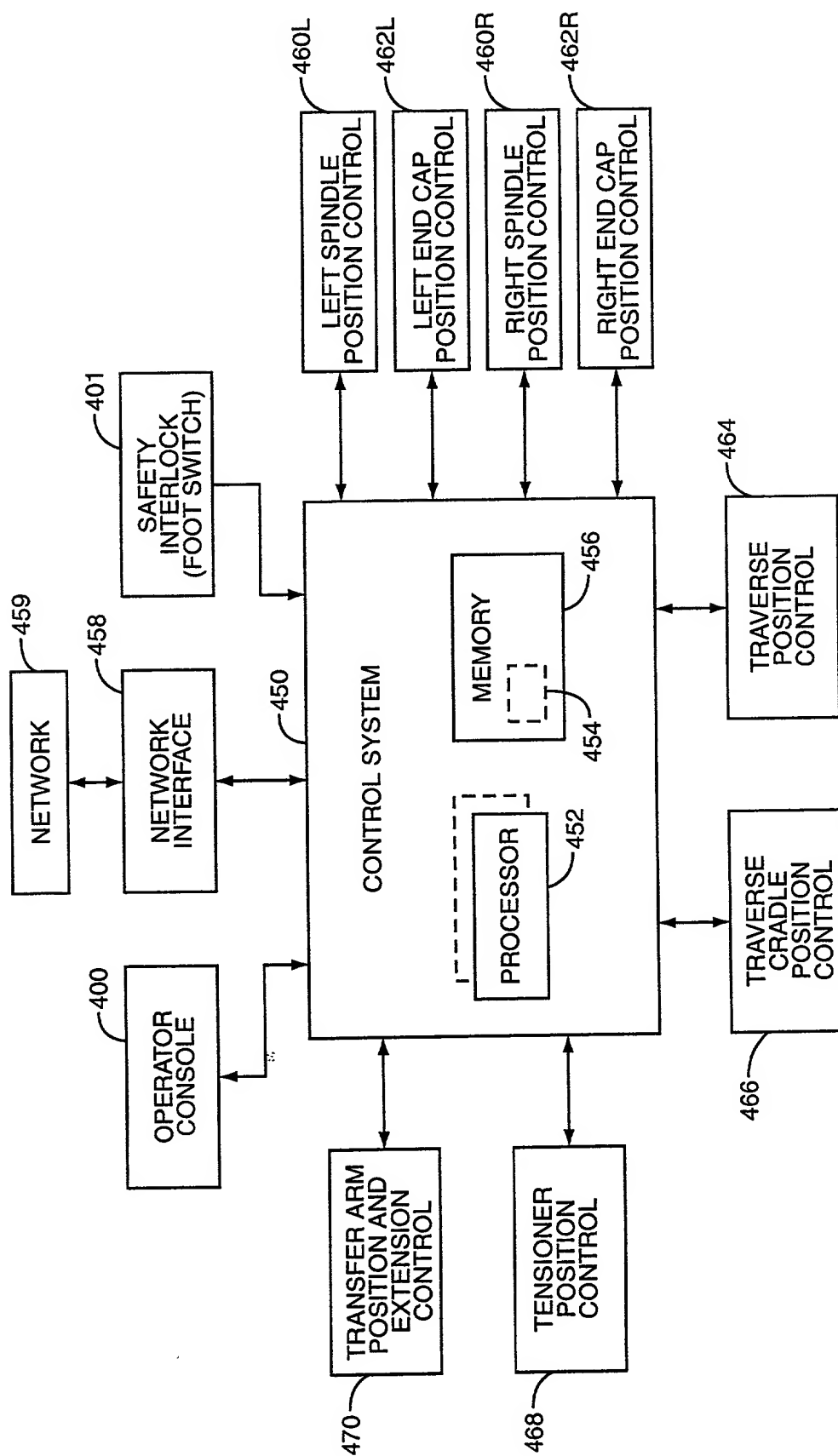


FIG. 14

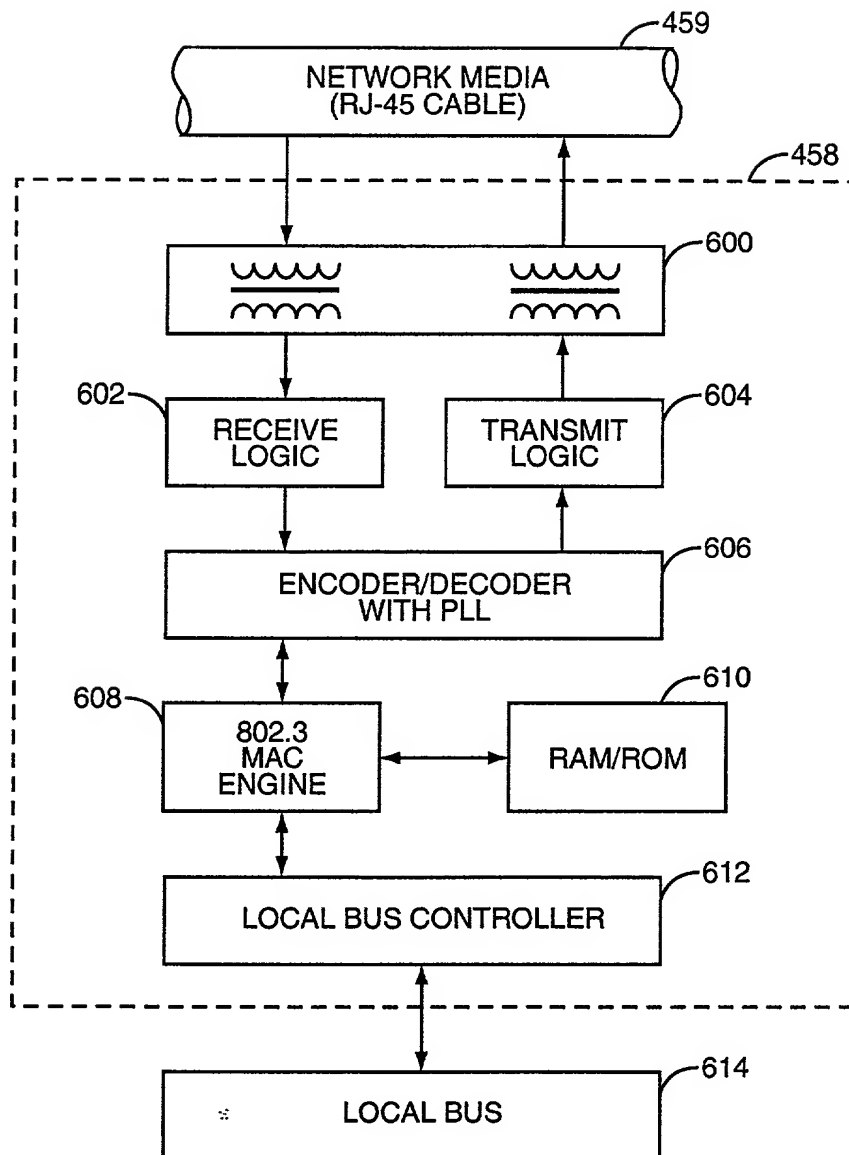


FIG. 15